

Wick Rotation on Degenerate Moyal Space

Thomas Ludwig

Joint work with H. Grosse, G. Lechner and R. Verch

Bayrischzell Workshop 2011

May 21, 2011

Introduction I

- “Wick Rotation” ... Analytically continuing a Lorentzian theory along “imaginary time” towards a Euclidean theory - and vice versa.

Introduction I

- “Wick Rotation” . . . Analytically continuing a Lorentzian theory along “imaginary time” towards a Euclidean theory - and vice versa.
- Wightman functions \leftrightarrow Schwinger functions [OS 1973, OS2 1975]

Introduction I

- “Wick Rotation” ... Analytically continuing a Lorentzian theory along “imaginary time” towards a Euclidean theory - and vice versa.
- Wightman functions \leftrightarrow Schwinger functions [OS 1973, OS2 1975]
- Euclidean net of algebras \rightarrow Haag-Kastler net in Minkowski space-time [Schl 1999]

$$\begin{array}{ccc} \mathcal{E} & \longleftrightarrow & \mathcal{E}_\theta \\ \updownarrow & & ? \\ \mathcal{M} & \longleftrightarrow & \mathcal{M}_\theta \end{array}$$

Introduction II

- Euclidean techniques are fundamental in constructive FT

Introduction II

- Euclidean techniques are fundamental in constructive FT
- QFT on noncommutative spaces with Euclidean metric has some success available:

Introduction II

- Euclidean techniques are fundamental in constructive FT
- QFT on noncommutative spaces with Euclidean metric has some success available:
- Scalar ϕ^4 -theory with additional terms proved renormalizable to all orders [GW 2004, RGMT 2009].

Introduction II

- Euclidean techniques are fundamental in constructive FT
- QFT on noncommutative spaces with Euclidean metric has some success available:
- Scalar ϕ^4 -theory with additional terms proved renormalizable to all orders [GW 2004, RGMT 2009].
- $S_{GW}[\phi] = S_{\phi^4}[\phi] + \int \frac{1}{2} \left(\frac{\Omega}{\theta}\right)^2 x^2 \phi^2$ features a renormalization group fixed point at $\Omega = 1 \rightarrow 2D$ -model constructed [W 2011], possibility of construction in $4D$. [RDGM 2006]

Introduction II

- Euclidean techniques are fundamental in constructive FT
- QFT on noncommutative spaces with Euclidean metric has some success available:
- Scalar ϕ^4 -theory with additional terms proved renormalizable to all orders [GW 2004, RGMT 2009].
- $S_{GW}[\phi] = S_{\phi^4}[\phi] + \int \frac{1}{2} \left(\frac{\Omega}{\theta}\right)^2 x^2 \phi^2$ features a renormalization group fixed point at $\Omega = 1 \rightarrow 2D$ -model constructed [W 2011], possibility of construction in $4D$. [RDGM 2006]
- At present no exact connection to noncommutative Lorentzian theories is known

Algebraic Approach: Spaces of Restricted Symmetry I

We start with a Euclidean net of von Neumann algebras $\mathcal{E}(\mathcal{O})$, $\mathcal{O} \subset \mathbb{R}^4$

Algebraic Approach: Spaces of Restricted Symmetry I

We start with a Euclidean net of von Neumann algebras $\mathcal{E}(\mathcal{O})$, $\mathcal{O} \subset \mathbb{R}^4$
and the reduced Euclidean group: $E_{\theta}(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$.

Algebraic Approach: Spaces of Restricted Symmetry I

We start with a Euclidean net of von Neumann algebras $\mathcal{E}(\mathcal{O})$, $\mathcal{O} \subset \mathbb{R}^4$

and the reduced Euclidean group: $E_\theta(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$.

$\mathcal{E}(\mathcal{O})$ shall satisfy isotony, $E_\theta(4)$ -covariance, locality.

Algebraic Approach: Spaces of Restricted Symmetry I

We start with a Euclidean net of von Neumann algebras $\mathcal{E}(\mathcal{O})$, $\mathcal{O} \subset \mathbb{R}^4$

and the reduced Euclidean group: $E_\theta(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$.

$\mathcal{E}(\mathcal{O})$ shall satisfy **isotony**, **$E_\theta(4)$ -covariance**, **locality**.

Algebraic Approach: Spaces of Restricted Symmetry II

Moreover, $\mathcal{E}(\mathcal{O})$ shall fulfill the so-called time-zero condition:

Algebraic Approach: Spaces of Restricted Symmetry II

Moreover, $\mathcal{E}(\mathcal{O})$ shall fulfill the so-called time-zero condition:

Time-Zero Condition

$$\mathcal{E}(\mathcal{O}) = \left(\bigcup_{K \subset \Sigma_e} \{ \alpha_{x,R}^{\mathcal{E}} \mathcal{A}_e^{\mathcal{E}}(K) : RK + x \subset \mathcal{O} \} \right)''$$

Algebraic Approach: Spaces of Restricted Symmetry II

Moreover, $\mathcal{E}(\mathcal{O})$ shall fulfill the so-called time-zero condition:

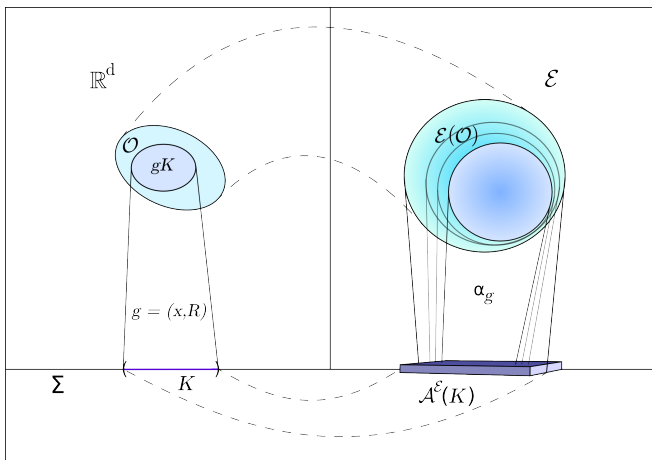
Time-Zero Condition

$$\mathcal{E}(\mathcal{O}) = \left(\bigcup_{K \subset \Sigma_e} \{ \alpha_{x,R}^{\mathcal{E}} \mathcal{A}_e^{\mathcal{E}}(K) : RK + x \subset \mathcal{O} \} \right)''$$

$$\Sigma_e \perp \mathbb{R}_+ e,$$

$\alpha_{x,R}^{\mathcal{E}} \dots$ automorphic $E_{\theta}(4)$ -action,

$$\mathcal{A}_e^{\mathcal{E}}(K) \subset \bigcap_{\mathcal{O} \supset K} \mathcal{E}(\mathcal{O}).$$



Schematic picture of the time-zero condition.

Time-Zero Condition

$$\mathcal{E}(\mathcal{O}) = \left(\bigcup_{K \subset \Sigma_e} \{ \alpha_{x,R}^{\mathcal{E}}(A) : RK + x \subset \mathcal{O}, A \in \mathcal{A}_e^{\mathcal{E}}(K) \} \right)''$$

$$\Sigma_e \perp \mathbb{R}_+ e,$$

$\alpha_{x,R}^{\mathcal{E}}$... automorphic $E_{\theta}(4)$ -action,

$$\mathcal{A}_e^{\mathcal{E}}(K) \subset \bigcap_{\mathcal{O} \supset K} \mathcal{E}(\mathcal{O}).$$

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Properties:

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Properties:

- $E_{\theta}(4) \ni (x, R) \mapsto \sigma(A\alpha_{x,R}^{\mathcal{E}}(B)C)$ continuous $\forall A, B, C \in \mathcal{E}$,

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Properties:

- $E_\theta(4) \ni (x, R) \mapsto \sigma(A\alpha_{x,R}^\mathcal{E}(B)C)$ continuous $\forall A, B, C \in \mathcal{E}$,
- $\sigma \circ \alpha_{x,R}^\mathcal{E} = \sigma \quad \forall (x, R) \in E_\theta(4)$,

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Properties:

- $E_\theta(4) \ni (x, R) \mapsto \sigma(A\alpha_{x,R}^\mathcal{E}(B)C)$ continuous $\forall A, B, C \in \mathcal{E}$,
- $\sigma \circ \alpha_{x,R}^\mathcal{E} = \sigma \quad \forall (x, R) \in E_\theta(4)$,
- $\exists e \in \mathbb{R}^4, |e| = 1$ such that
 $\sigma(\alpha_{r_e}(A^*)A) \geq 0 \quad \forall A \in \mathcal{E}^+ := \{\mathcal{E}(\mathcal{O}), \mathcal{O} \subset \mathbb{R}_+e + \Sigma_e\}$.

Algebraic Approach: Spaces of Restricted Symmetry III

Last input: regular reflection-positive Euclidean functional σ .

Properties:

- $E_\theta(4) \ni (x, R) \mapsto \sigma(A\alpha_{x,R}^\mathcal{E}(B)C)$ continuous $\forall A, B, C \in \mathcal{E}$,
- $\sigma \circ \alpha_{x,R}^\mathcal{E} = \sigma \quad \forall (x, R) \in E_\theta(4)$,
- $\exists e \in \mathbb{R}^4, |e| = 1$ such that
 $\sigma(\alpha_{r_e}(A^*)A) \geq 0 \quad \forall A \in \mathcal{E}^+ := \{\mathcal{E}(\mathcal{O}), \mathcal{O} \subset \mathbb{R}_+e + \Sigma_e\}$.

r_e denotes the e -reflection, $r_e : x \mapsto x - 2(e, x)e$.

Algebraic Approach: Spaces of Restricted Symmetry IV

Via a construction similar to GNS we obtain the Hilbert space $\mathcal{H}^{\mathcal{M}}$.

Algebraic Approach: Spaces of Restricted Symmetry IV

Via a construction similar to GNS we obtain the Hilbert space $\mathcal{H}^{\mathcal{M}}$.

There, “spatial transformations” (x, R) :

$[\alpha_{x,R}^{\mathcal{E}}, \alpha_{r_e}] = 0$, directly \rightarrow str.-cont. group $U_e((0, \mathbf{x}), R(0, \alpha))$ of unitaries.

Algebraic Approach: Spaces of Restricted Symmetry IV

Via a construction similar to GNS we obtain the Hilbert space $\mathcal{H}^{\mathcal{M}}$.

There, “spatial transformations” (\mathbf{x}, R) :

$[\alpha_{\mathbf{x}, R}^{\mathcal{E}}, \alpha_{r_e}] = 0$, directly \rightarrow str.-cont. group $U_e((0, \mathbf{x}), R(0, \alpha))$ of unitaries.

Let $[A]_{\sigma}$ be equivalence class w.r.t. the product $\langle A, B \rangle := \sigma(\alpha_{r_e}(A^*)B)$.

Then define operators

Algebraic Approach: Spaces of Restricted Symmetry IV

Via a construction similar to GNS we obtain the Hilbert space $\mathcal{H}^{\mathcal{M}}$.

There, “spatial transformations” (\mathbf{x}, R) :

$[\alpha_{\mathbf{x}, R}^{\mathcal{E}}, \alpha_{r_e}] = 0$, directly \longrightarrow str.-cont. group $U_e((0, \mathbf{x}), R(0, \alpha))$ of unitaries.

Let $[A]_{\sigma}$ be equivalence class w.r.t. the product $\langle A, B \rangle := \sigma(\alpha_{r_e}(A^*)B)$.

Then define operators

$$\begin{aligned} V(t)[A]_{\sigma} &:= [\alpha_{((t, 0, 0, 0), 1)}(A)]_{\sigma}, \text{ for } t \geq 0 \\ \tilde{V}(\beta)[A]_{\sigma} &:= [\alpha_{(0, R(\beta, 0))}(A)]_{\sigma}, \quad R(\beta, 0) := R(\beta) \oplus 1 \end{aligned}$$

Algebraic Approach: Spaces of Restricted Symmetry V

Some remarkable works concern continuation of such representations. Most notably: Fröhlich, Osterwalder & Seiler [FOS 1983], Fröhlich [F 1980] ; Klein and Landau [KL 1981, KL2 1983]

Shown there: operators generalizing $V(t)$ and $\tilde{V}(\beta)$ are **generated by** densely def. **symm. operators** which **continue to self-adjoint** operators on \mathcal{H}^M .

Jorgensen and Ólafsson [JO 1999] gave a general treatment.

Algebraic Approach: Spaces of Restricted Symmetry VI

In this way:

Imaginary time-translations $V(t)$ and x_0, x_1 -rotations $\tilde{V}(\beta)$

$\xrightarrow{\text{analytically}}$ real time-translations e^{itH} and x_0, x_1 -boosts $e^{i\beta L}$:

Algebraic Approach: Spaces of Restricted Symmetry VI

In this way:

Imaginary time-translations $V(t)$ and x_0, x_1 -rotations $\tilde{V}(\beta)$

$\xrightarrow{\text{analytically}}$ real time-translations e^{itH} and x_0, x_1 -boosts $e^{i\beta L}$: Define

$$U((t, \mathbf{x}), \Lambda(\beta, \alpha)) := e^{itH} U_e((0, \mathbf{x}), \Lambda(0, \alpha)) e^{i\beta L}$$

Algebraic Approach: Spaces of Restricted Symmetry VI

In this way:

Imaginary time-translations $V(t)$ and x_0, x_1 -rotations $\tilde{V}(\beta)$
analytically \longrightarrow real time-translations e^{itH} and x_0, x_1 -boosts $e^{i\beta L}$: Define

$$U((t, \mathbf{x}), \Lambda(\beta, \alpha)) := e^{itH} U_e((0, \mathbf{x}), \Lambda(0, \alpha)) e^{i\beta L}$$

\rightarrow It results a well-defined $\mathcal{P}_\theta(4)$ -action, denote by $\alpha_g^{\mathcal{M}}$.

$$\mathcal{P}_\theta(4) := (O(1, 1) \times SO(2)) \ltimes \mathbb{R}^4.$$

Proposition

- The operators $U(x, \Lambda(\beta, \alpha))$ form a unitary, weakly continuous representation of the reduced Poincaré group $\mathcal{P}_\theta(4)$ on \mathcal{H}^M .

Proposition

- The operators $U(x, \Lambda(\beta, \alpha))$ form a unitary, weakly continuous representation of the reduced Poincaré group $\mathcal{P}_\theta(4)$ on \mathcal{H}^M .
- The vacuum vector $\Omega := [1]_\sigma$ is invariant under $U(g)$ for all $g \in \mathcal{P}_\theta(4)$.

Proposition

- The operators $U(x, \Lambda(\beta, \alpha))$ form a unitary, weakly continuous representation of the reduced Poincaré group $\mathcal{P}_\theta(4)$ on \mathcal{H}^M .
- The vacuum vector $\Omega := [1]_\sigma$ is invariant under $U(g)$ for all $g \in \mathcal{P}_\theta(4)$.
- The joint spectrum of the generators H, P_1, P_2, P_3 of the translations lies in the closed lightwedge

$$Y := \{p \in \mathbb{R}^4 : p_0 \geq |p_1|\}.$$

Warped Convolution I

The so-called warped convolutions display a well-defined way of deforming an algebraic theory [BS 2008]:

Warped Convolution I

The so-called warped convolutions display a well-defined way of deforming an algebraic theory [BS 2008]:

For a von Neumann algebra element A and a skew-symmetric matrix

$$\theta := \begin{pmatrix} 0 & 0 \\ 0 & \theta_1 \end{pmatrix}, \quad \theta_1 := \begin{pmatrix} 0 & \vartheta \\ -\vartheta & 0 \end{pmatrix}, \quad \vartheta \in \mathbb{R}$$

(commutative time)

it is defined as follows

Warped Convolution I

The so-called warped convolutions display a well-defined way of deforming an algebraic theory [BS 2008]:

For a von Neumann algebra element A and a skew-symmetric matrix

$$\theta := \begin{pmatrix} 0 & 0 \\ 0 & \theta_1 \end{pmatrix}, \quad \theta_1 := \begin{pmatrix} 0 & \vartheta \\ -\vartheta & 0 \end{pmatrix}, \quad \vartheta \in \mathbb{R}$$

(commutative time)

it is defined as follows

$$A_\theta \Phi := \iint dx dy e^{ixy} \alpha_{\theta x}(A) U(y) \Phi \quad , \quad \Phi \in \mathcal{D} \text{ (suitable)}$$

Warped Convolution I

The so-called warped convolutions display a well-defined way of deforming an algebraic theory [BS 2008]:

For a von Neumann algebra element A and a skew-symmetric matrix

$$\theta := \begin{pmatrix} 0 & 0 \\ 0 & \theta_1 \end{pmatrix}, \quad \theta_1 := \begin{pmatrix} 0 & \vartheta \\ -\vartheta & 0 \end{pmatrix}, \quad \vartheta \in \mathbb{R}$$

(commutative time)

it is defined as follows

$$A_\theta \Phi := \iint dx dy e^{ixy} \alpha_{\theta x}(A) U(y) \Phi, \quad \Phi \in \mathcal{D} \text{ (suitable)}$$

$$U(y) := e^{iPy} = \int dE(p) e^{ipy}$$

Warped Convolution II

The symmetry group $E_\theta(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$ was chosen such that

$$R\theta = \theta R \quad \text{for all } R \in E_\theta(4).$$

Warped Convolution II

The symmetry group $E_\theta(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$ was chosen such that

$$R\theta = \theta R \quad \text{for all } R \in E_\theta(4).$$

Thus, the (space-space) noncommutative deformation of $\mathcal{E}(\mathcal{O})$ defined by

$$\mathcal{E}_\theta(\mathcal{O}) := \{A_\theta \mid A \in \mathcal{E}(\mathcal{O})\}$$

is also $E_\theta(4)$ -covariant.

Warped Convolution II

The symmetry group $E_\theta(4) = (O(2) \times SO(2)) \ltimes \mathbb{R}^4$ was chosen such that

$$R\theta = \theta R \quad \text{for all } R \in E_\theta(4).$$

Thus, the (space-space) noncommutative deformation of $\mathcal{E}(\mathcal{O})$ defined by

$$\mathcal{E}_\theta(\mathcal{O}) := \{A_\theta \mid A \in \mathcal{E}(\mathcal{O})\}$$

is also $E_\theta(4)$ -covariant.

Remark: Remains true in case of full rank noncommutativity Q for $(SO(2) \times SO(2)) \ltimes \mathbb{R}^4$.

Warped Convolution III

In order to apply our result to the deformed theory, we face **changes in the algebraic setting**:

Warped Convolution III

In order to apply our result to the deformed theory, we face changes in the algebraic setting:

- Arbitrary open subsets \mathcal{O} of \mathbb{R}^4 are **unstable w.r.t. the deformation**:
i.e., $\exists A_\theta, B_\theta \in \mathcal{E}_\theta(\mathcal{O}) : A_\theta B_\theta \notin \mathcal{E}_\theta(\mathcal{O})$.

Warped Convolution III

In order to apply our result to the deformed theory, we face changes in the algebraic setting:

- Arbitrary open subsets \mathcal{O} of \mathbb{R}^4 are unstable w.r.t. the deformation:
i.e., $\exists A_\theta, B_\theta \in \mathcal{E}_\theta(\mathcal{O}) : A_\theta B_\theta \notin \mathcal{E}_\theta(\mathcal{O})$.
- Not clear: do arbitrary nets **keep the time-zero condition** after deformation?

Warped Convolution III

In order to apply our result to the deformed theory, we face changes in the algebraic setting:

- Arbitrary open subsets \mathcal{O} of \mathbb{R}^4 are unstable w.r.t. the deformation: i.e., $\exists A_\theta, B_\theta \in \mathcal{E}_\theta(\mathcal{O}) : A_\theta B_\theta \notin \mathcal{E}_\theta(\mathcal{O})$.
- Not clear: do arbitrary nets keep the time-zero condition after deformation?

At least two possibilities:

- Take $\mathcal{E}_\theta(\mathcal{O})$ to be the algebra generated by all warped elements of $\mathcal{E}(\mathcal{O})$

Warped Convolution III

In order to apply our result to the deformed theory, we face changes in the algebraic setting:

- Arbitrary open subsets \mathcal{O} of \mathbb{R}^4 are unstable w.r.t. the deformation: i.e., $\exists A_\theta, B_\theta \in \mathcal{E}_\theta(\mathcal{O}) : A_\theta B_\theta \notin \mathcal{E}_\theta(\mathcal{O})$.
- Not clear: do arbitrary nets keep the time-zero condition after deformation?

At least two possibilities:

- Take $\mathcal{E}_\theta(\mathcal{O})$ to be the algebra generated by all warped elements of $\mathcal{E}(\mathcal{O}) \rightarrow$ v.N. algebra by construction, but further properties are to be investigated.

Warped Convolution III

In order to apply our result to the deformed theory, we face changes in the algebraic setting:

- Arbitrary open subsets \mathcal{O} of \mathbb{R}^4 are unstable w.r.t. the deformation: i.e., $\exists A_\theta, B_\theta \in \mathcal{E}_\theta(\mathcal{O}) : A_\theta B_\theta \notin \mathcal{E}_\theta(\mathcal{O})$.
- Not clear: do arbitrary nets keep the time-zero condition after deformation?

At least two possibilities:

- Take $\mathcal{E}_\theta(\mathcal{O})$ to be the algebra generated by all warped elements of $\mathcal{E}(\mathcal{O}) \rightarrow$ v.N. algebra by construction, but further properties are to be investigated.
- Instead, consider nets indexed by **better suitable regions** in \mathbb{R}^4 .

For now, we follow the second option.

Warped Convolution IV

Therefore, we define the **cylindrical subsets**

$$C := \{ \mathcal{O} \subsetneq \mathbb{R}^4 \mid \mathcal{O}_2 \text{ bounded, } \mathcal{O} + x = \mathcal{O} \forall x \in 0 \times \mathbb{R}^2 \},$$

where \mathcal{O}_2 denotes the projection of \mathcal{O} onto commutative $\mathbb{R}^2 \times 0$,

Warped Convolution IV

Therefore, we define the cylindrical subsets

$$C := \{ \mathcal{O} \subsetneq \mathbb{R}^4 \mid \mathcal{O}_2 \text{ bounded, } \mathcal{O} + x = \mathcal{O} \forall x \in 0 \times \mathbb{R}^2 \},$$

where \mathcal{O}_2 denotes the projection of \mathcal{O} onto commutative $\mathbb{R}^2 \times 0$, as well as the **time-zero stripes**:

$$S := \{ K \subsetneq \Sigma_e \mid K_1 \text{ bounded, } K + x = K \forall x \in 0 \times \mathbb{R}^2 \}.$$

Warped Convolution IV

Therefore, we define the cylindrical subsets

$$C := \{ \mathcal{O} \subsetneq \mathbb{R}^4 \mid \mathcal{O}_2 \text{ bounded, } \mathcal{O} + x = \mathcal{O} \forall x \in 0 \times \mathbb{R}^2 \},$$

where \mathcal{O}_2 denotes the projection of \mathcal{O} onto commutative $\mathbb{R}^2 \times 0$, as well as the time-zero stripes:

$$S := \{ K \subsetneq \Sigma_e \mid K_1 \text{ bounded, } K + x = K \forall x \in 0 \times \mathbb{R}^2 \}.$$

→ For $C \in \mathcal{C}$, $\mathcal{E}_\theta(C)$ is **stable under warped convolutions**.

Warped Convolution IV

Therefore, we define the cylindrical subsets

$$C := \{ \mathcal{O} \subsetneq \mathbb{R}^4 \mid \mathcal{O}_2 \text{ bounded, } \mathcal{O} + x = \mathcal{O} \forall x \in 0 \times \mathbb{R}^2 \},$$

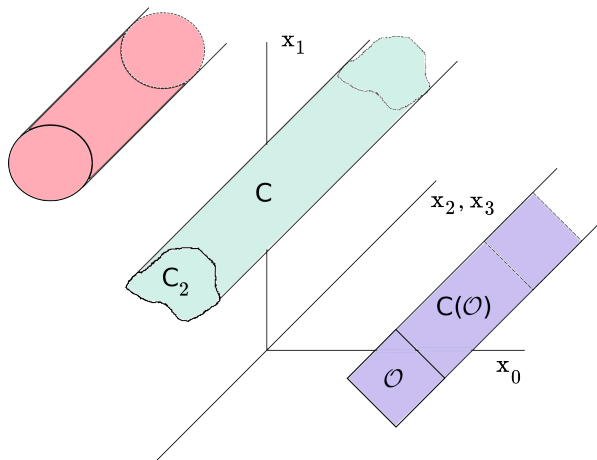
where \mathcal{O}_2 denotes the projection of \mathcal{O} onto commutative $\mathbb{R}^2 \times 0$, as well as the time-zero stripes:

$$S := \{ K \subsetneq \Sigma_e \mid K_1 \text{ bounded, } K + x = K \forall x \in 0 \times \mathbb{R}^2 \}.$$

→ For $C \in \mathcal{C}$, $\mathcal{E}_\theta(C)$ is stable under warped convolutions.

Warning: Does **not** mean **localization** in C !

Cylindrical Subsets



Warped Convolution: (TZ)

What about the time-zero condition?

Warped Convolution: (TZ)

What about the time-zero condition?

Lemma: $E_\theta(4)$ enough for C

① $\forall C \in \mathcal{C}, \forall S \in \mathcal{S} \exists g \in E_\theta(4) :$

$$gS \subset C$$

② If $g \in E(4)$ s.t. for $S \in \mathcal{S}$ we have $gS \subset C$ for a $C \in \mathcal{C}$

$$\Rightarrow g \in E_\theta(4)$$

Warped Convolution: (TZ)

What about the time-zero condition?

Lemma: $E_\theta(4)$ enough for \mathcal{C}

① $\forall C \in \mathcal{C}, \forall S \in \mathcal{S} \exists g \in E_\theta(4) :$

$$gS \subset C$$

② If $g \in E(4)$ s.t. for $S \in \mathcal{S}$ we have $gS \subset C$ for a $C \in \mathcal{C}$

$$\Rightarrow g \in E_\theta(4)$$

Corollary

If $\mathcal{E}(C)$ is $E(4)$ -cov. and satisfies (TZ)
 $\Rightarrow \mathcal{E}_\theta(C)$ is $E_\theta(4)$ -cov. and satisfies (TZ) $_\theta$

Warped Convolution: $(TZ)_\theta$

Proof (Cor., sketched).

Indeed, contemplate such $\mathcal{E}(C)$. From the lemma we have

$$\begin{aligned} & \{\alpha_g \mathcal{A}_0(S) \mid S \in \mathcal{S}, g \in E(d), gS \subset C\} \\ = & \{\alpha_g \mathcal{A}_0(S) \mid S \in \mathcal{S}, g \in E_\theta(d), gS \subset C\} \end{aligned}$$

$\mathcal{E}_\theta(C)$ is well-defined and $E_\theta(4)$ -covariant \Rightarrow

$$\mathcal{E}_\theta(C) = \left(\bigcup_{S \in \mathcal{S}} \{\alpha_g \mathcal{A}_\theta(S) \mid S \in \mathcal{S}, g \in E_\theta(d), gS \subset C\} \right)''$$



Warped Convolution: Minkowskian Net

Locality properties of warped convolutions derived in [BLS 2010] remain valid here. Combining our results leads to

Warped Convolution: Minkowskian Net

Locality properties of warped convolutions derived in [BLS 2010] remain valid here. Combining our results leads to

Minkowskian Net

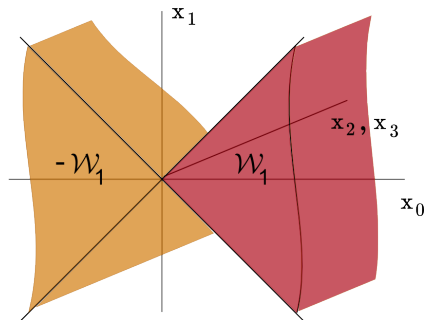
$$\mathcal{M}_\theta(\mathcal{C}) := \left(\bigcup_{S \subset \mathcal{C}} \{ \alpha_g^{\mathcal{M}}(\pi_\sigma(A)) \mid g \in \mathcal{P}_\theta(4), gS \subset \mathcal{C}, A \in \mathcal{A}_\theta^\mathcal{E}(K) \} \right)''$$

defines a Haag-Kastler net with modified locality (wedge locality).

$\pi_\sigma \dots$ repr. of \mathcal{E}_θ on $\mathcal{H}^{\mathcal{M}}$.

Wedge Locality

$$\mathcal{W}_1 := \{x \in \mathbb{R}^4 \mid x_1 > |x_0|\}$$



$$A \in \mathcal{M}(\mathcal{W}_1) \quad , \quad B \in \mathcal{M}(-\mathcal{W}_1) \\ \Rightarrow [A_\theta, B_{-\theta}] = 0$$

Summary

- Input data: $E(4)$ -covariant Euclidean net $\mathcal{E}(\mathcal{O})$ of v.N. algebras, regular reflection-positive Euclidean functional σ and the (restrictive!) time-zero condition

Summary

- Input data: $E(4)$ -covariant Euclidean net $\mathcal{E}(\mathcal{O})$ of v.N. algebras, **regular reflection-positive Euclidean functional** σ and the (restrictive!) time-zero condition

Summary

- Input data: $E(4)$ -covariant Euclidean net $\mathcal{E}(\mathcal{O})$ of v.N. algebras, regular reflection-positive Euclidean functional σ and **the (restrictive!) time-zero condition**

Summary

- Input data: $E(4)$ -covariant Euclidean net $\mathcal{E}(\mathcal{O})$ of v.N. algebras, regular reflection-positive Euclidean functional σ and the (restrictive!) time-zero condition
- Deformation: Build the algebra $\mathcal{E}_\theta(C(\mathcal{O}))$ in terms of warped convolutions.

Summary

- Input data: $E(4)$ -covariant Euclidean net $\mathcal{E}(\mathcal{O})$ of v.N. algebras, regular reflection-positive Euclidean functional σ and the (restrictive!) time-zero condition
- Deformation: Build the algebra $\mathcal{E}_\theta(C(\mathcal{O}))$ in terms of warped convolutions.
→ \mathcal{E}_θ is $E_\theta(4)$ -cov. & well-def. on C .

Commuting Diagram

$$\begin{array}{ccc} \mathcal{E} & \longleftrightarrow & \mathcal{E}_\theta \\ \updownarrow & & \downarrow \\ \mathcal{M} & \longleftrightarrow & \mathcal{M}_\theta \end{array}$$

\updownarrow ... known Wick rotation
 \longrightarrow ... warped convolution
 \longleftarrow ... commutative limit, i.e. $\vartheta \rightarrow 0$
 \downarrow ... this talk

Remarks:

- Generalization of the group continuation to space-time dimension $d = s + 2n$ has been done.

Remarks:

- Generalization of the group continuation to space-time dimension $d = s + 2n$ has been done.
- The lemma concerning $(TZ)_\theta$ has up until now be generalized to $d \leq 4$.

Remarks:

- Generalization of the group continuation to space-time dimension $d = s + 2n$ has been done.
- The lemma concerning $(TZ)_\theta$ has up until now be generalized to $d \leq 4$.

Open tasks:

- Drop or at least relax the time-zero condition

Remarks:

- Generalization of the group continuation to space-time dimension $d = s + 2n$ has been done.
- The lemma concerning $(TZ)_\theta$ has up until now be generalized to $d \leq 4$.

Open tasks:

- Drop or at least relax the time-zero condition
- Obtain similar results for noncommutative time

Remarks:

- Generalization of the group continuation to space-time dimension $d = s + 2n$ has been done.
- The lemma concerning $(TZ)_\theta$ has up until now be generalized to $d \leq 4$.

Open tasks:

- Drop or at least relax the time-zero condition
- Obtain similar results for noncommutative time
- “Covariantize” to have full symmetry group $E(4)$ at hand.

THANK YOU FOR YOUR ATTENTION !



K. Osterwalder, R. Schrader.

Axioms for Eucliden Green's Functions,
Comm.Math.Phys. 31; 83–112, 1973.



K. Osterwalder, R. Schrader.

Axioms for Eucliden Green's Functions II,
Comm.Math.Phys. 42; 281, 1975.



J. Fröhlich.

Unbounded, Symmetric Semigroups on a Separable Hilbert Space Are Essentially Selfadjoint,
Adv. Appl. Math. 1, 237-256, 1980



A. Klein, Landau.

Construction Of A Unique Self-Adjoint Generator for a Symmetric Local Semigroup,
J.Funct.Anal. 44; 121, 1981.



A. Klein, Landau.

From the Euclidean group to the Poincaré group via Osterwalder-Schrader positivity,
Comm.Math.Phys. 87; 469–484, 1983.



J. Fröhlich and K. Osterwalder and E. Seiler.

On Virtual representations of symmetric spaces and their analytic continuation

Annals Math. 118; 461–489, 1983.



D. Schlingemann.

From Euclidean Field Theory to Quantum Field Theory,
Rev. Math. Phys. 11; 1151–1178, 1999.



P. Jorgensen, G. Ólafsson.

Unitary Representations and Osterwalder-Schrader Duality,
Preprint: <http://arxiv.org/abs/math/9908031>, 1999.



H. Grosse, R. Wulkenhaar.

Renormalization of ϕ^4 theory on noncommutative \mathbb{R}^4 in the matrix base,
Comm.Math.Phys. 256; 305-374, 2004.



V. Rivasseau, M. Disertori, R. Gurau, J. Magnen.

Vanishing of Beta Function of Non Commutative ϕ_4^4 Theory to all orders,
Phys.Lett. B649; 95-102, 2006.



D. Buchholz, S.J. Summers.

Warped Convolutions: A Novel Tool in the Construction of Quantum Field Theories,
Preprint: <http://arxiv.org/abs/0806.0349>, 2008.



V. Rivasseau, R. Gurau, J. Magnen, A. Tanasa.

A Translation-invariant renormalizable non-commutative scalar model,
Comm.Math.Phys. 287; 275-290, 2009.



D. Buchholz, G. Lechner, S.J. Summers.

Warped Convolutions, Rieffel Deformations and the Construction of Quantum Field Theories,

Preprint: <http://arxiv.org/abs/1005.2656>, 2010.



Z. Wang,

Construction of 2-dimensional Grosse-Wulkenhaar Model,

Preprint: <http://arxiv.org/abs/1104.3750v1>, 2011.