

# Graded Geometry and Gravity

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## Outline

- ▶ Interaction via deformation
- ▶ Graded spacetime mechanics
- ▶ Generalized geometry
- ▶ Graded geometry and gravity

# Interaction via deformation

## Interaction via deformation

example: relativistic particle in einbein formalism

$$S = \int d\tau \left( \frac{1}{2e} g_{\mu\nu}(x) \dot{x}^\mu \dot{x}^\nu - \frac{1}{2} e m^2 + \mathbf{A}_\mu(x) \dot{x}^\mu \right) \rightsquigarrow p_\mu = \frac{1}{e} g_{\mu\nu} \dot{x}^\nu + A_\mu$$

$$S_H = \int p_\mu dx^\mu - \frac{1}{2} e ((p_\mu - A_\mu)^2 + m^2) d\tau \quad p_\mu: \text{canonical momentum}$$

$$\boxed{S_H = \int (p_\mu + A_\mu) dx^\mu - \frac{1}{2} e (p_\mu^2 + m^2) d\tau} \quad p_\mu: \text{physical momentum}$$

$$\omega' = d(p_\mu + A_\mu) \wedge dx^\mu \rightsquigarrow$$

$$\boxed{\{p_\mu, p_\nu\}' = \mathbf{F}_{\mu\nu}, \{x^\mu, p_\nu\}' = \delta_\nu^\mu, \{x^\mu, x^\nu\}' = 0}$$

$$\boxed{\{p_\lambda, \{p_\mu, p_\nu\}'\}' + \text{cycl.} = (dF)_{\lambda\mu\nu} = (*j_m)_{\lambda\mu\nu}} \quad \leftarrow \text{magnetic 4-current}$$

magnetic sources  $\Leftrightarrow$  non-associativity

# Interaction via deformation

gauge field  $A \rightsquigarrow$  deformation  $\omega' \dots$  vice versa  $\omega' \rightsquigarrow A$ :

## Moser's lemma

Let  $\omega_s = \omega + sF$ , with  $\omega_s$  symplectic for  $s \in [0, 1]$ .

note:  $d\omega_s = 0 \Rightarrow dF = 0 \Rightarrow$  locally  $F = dA$

$\omega' \equiv \omega_1$  and  $\omega$  are related by a change of phase space coordinates generated by the flow of a vector field  $V_s$  defined up to gauge transformations by the gauge field  $i_{V_s}\omega_s = A$ , i.e.  $V_s = \theta_s(A, -)$ .

Proof:  $\mathcal{L}_{V_s}\omega_s = i_{V_s}d\omega_s + d i_{V_s}\omega_s = 0 + dA = \frac{d}{ds}\omega_s$ . Moser 1965

*Example:* For  $\omega = dp_i \wedge dx^i$  and  $A = A_i(x)dx^i$ :  $V_s = A_i(x)\frac{\partial}{\partial p_i}$

Quantum version of the lemma:

Jurco, PS, Wess 2000-2002

# Interaction via deformation

## Quantization

- ▶ canonical? depends... (✓)
- ▶ deformation quantization ✓
- ▶ path integral ✓

## Deformed CCR:

$$[p_\mu, p_\nu] = i\hbar F_{\mu\nu}, \quad [x^\mu, p_\nu] = i\hbar \delta_\nu^\mu, \quad [x^\mu, x^\nu] = 0$$

Let  $\mathbf{p} = \gamma^\mu p_\mu$  and  $H = \frac{1}{2}\mathbf{p}^2 \rightsquigarrow$  correct coupling of fields to spin

$$H = \frac{1}{8}(\{\gamma^\mu, \gamma^\nu\}\{p_\mu, p_\nu\} + [\gamma^\mu, \gamma^\nu][p_\mu, p_\nu]) = \frac{1}{2}p^2 - \frac{i\hbar}{2}S^{\mu\nu}F_{\mu\nu}$$

Lorentz-Heisenberg equations of motion (ignoring spin)

$$\dot{p}_\mu = \frac{i}{\hbar}[H, p_\mu] = \frac{1}{2}(F_{\mu\nu}\dot{x}^\nu + \dot{x}^\nu F_{\mu\nu}) \quad \text{with} \quad \dot{x}^\nu = \frac{i}{\hbar}[H, x^\nu] = p^\nu$$

this formalism allows  $dF \neq 0$ : magnetic sources, non-associativity

# Interaction via deformation

local non-associativity:  $\frac{1}{3}[p_\lambda, [p_\mu, p_\nu]] dx^\lambda dx^\mu dx^\nu = \hbar^2 dF = \hbar^2 *j_m$

$j_m \neq 0 \Leftrightarrow$  no operator representation of the  $p_\mu$ !

spacetime translations are still generated by  $p_\mu$ , but magnetic flux  $\Phi_m$  leads to path-dependence with phase  $e^{i\phi}$ ; where  $\phi = iq_e \Phi_m / \hbar$

globally:

$$\Phi_m = \int_S F = \int_{\partial S} A \quad \leftrightarrow \text{non-commutativity}$$

$$\Phi_m = \int_{\partial V} F = \int_V dF = \int_V *j_m = q_m \quad \leftrightarrow \text{non-associativity}$$

global associativity requires  $\phi \in 2\pi\mathbb{Z} \Rightarrow \boxed{\frac{q_e q_m}{2\pi\hbar} \in \mathbb{Z}}$  Dirac quantization

non-relativistic version: Jackiw 1985, 2002

# Graded spacetime mechanics

Now try to do the same for gravity! Deformation maybe fine for curvature  $R_{\mu\nu}$ , however, the metric  $g_{\mu\nu}$  is symmetric but  $\{, \}$  is not.

- ▶ consider derived brackets

$$g^{\mu\nu} \sim \{ \{x^\mu, H\}, x^\nu \} , \quad \{H, H\} = 0$$

- ▶ use graded geometry, i.e. odd variables and/or odd brackets
- ▶  $\rightsquigarrow$  algebraic approach to the geodesic equation, connections, curvature, etc. Properties like metricity follow from associativity. Local inertial coordinates are reinterpreted as Darboux charts
- ▶ the classical formulation requires graded variables ( $\sim$  differentials), quantization leads to  $\gamma$ -matrices and Clifford algebras

classical	$\leftrightarrow$	quantum
$\theta^\mu$	$\leftrightarrow$	$\gamma^\mu$
$\theta^\mu \theta^\nu = -\theta^\nu \theta^\mu$	$\leftrightarrow$	$\frac{1}{2}[\gamma^\mu, \gamma^\nu]_-$
$\frac{1}{2}\{\theta^\mu, \theta^\nu\} = g^{\mu\nu}$	$\leftrightarrow$	$\frac{1}{2}[\gamma^\mu, \gamma^\nu]_+ = g^{\mu\nu}$

# Graded spacetime mechanics

## Graded Poisson algebra

$$\{\theta_a^\mu, \theta_a^\nu\} = 2g_0^{\mu\nu}(x) \quad \{p_c^\mu, x_0^\nu\} = \delta_{0c}^\nu \quad \{p_\mu, f(x)\} = \partial_\mu f(x)$$

Since  $g^{\mu\nu}(x)$  has degree 0, the Poisson bracket must have degree  $b = -2a$  for  $\theta^\mu$  of degree  $a$ , i.e. it is an **even** bracket.

Since  $g^{\mu\nu}(x)$  is symmetric, we must have  $-(-1)^{b+a^2} \stackrel{!}{=} +1$ , i.e.  $a$  is **odd**.

wlog:  $\{, \}$  is of degree  $b = -2$ ,  $\theta^\mu$  are Grassmann variables of degree 1,  $\theta^\mu \theta^\nu = -\theta^\nu \theta^\mu$ , and the momenta  $p_\mu$  have degree  $c = -b = 2$

$\Leftrightarrow$  a metric structure on  $TM$  and natural symplectic structure on  $T^*M$ , shifted in degree and combined into a graded Poisson structure on

$$T^*[2]_{p_\mu} \oplus T[1]_{\theta^\mu, x^\mu} M$$



# Graded spacetime mechanics

Graded Poisson algebra on  $T^*[2] \oplus T[1]M$

$$\{\theta^\mu_1, \theta^\nu_1\} = 2g^{\mu\nu}_0(x) \quad \{p_\mu, x^\nu_0\} = \delta^\nu_\mu \quad \{p_\mu, f(x)\} = \partial_\mu f(x)$$

associativity/Jacobi identity  $\Leftrightarrow$  metric connection

$$\{p_\mu, \{\theta^\alpha, \theta^\beta\}\} = 2\partial_\mu g^{\alpha\beta} = \{\{p_\mu, \theta^\alpha\}, \theta^\beta\} + \{\theta^\alpha, \{p_\mu, \theta^\beta\}\}$$

$$\{p_\mu, \theta^\alpha_1\} = \nabla_\mu \theta^\alpha = \Gamma^\alpha_{\mu\beta} \theta^\beta_1$$

and curvature

$$\{\{p_\mu, p_\nu\}, \theta^\alpha\} = [\nabla_\mu, \nabla_\nu] \theta^\alpha = \theta^\beta R^\alpha_{\beta\mu\nu}$$

$$\Rightarrow \quad \{p_\mu, p_\nu\} = \frac{1}{4} \theta^\beta_1 \theta^\alpha_1 R_{\beta\alpha\mu\nu}$$

## symmetries = canonical transformations

- ▶ generator of degree 2 (degree-preserving):

$$v^\alpha(x)p_\alpha + \frac{1}{2}\Omega_{\alpha\beta}(x)\theta^\alpha\theta^\beta \rightsquigarrow \text{local Poincare algebra}$$

- ▶ generators of degree 1:

$$V = V_\alpha(x)\theta^\alpha \rightsquigarrow \{V, W\} = 2g(V, W)$$

- ▶ generators of degree 3:

$$\Theta = \theta^\alpha p_\alpha \quad \left(+\frac{1}{6}C_{\alpha\beta\gamma}\theta^\alpha\theta^\beta\theta^\gamma\right)$$

- ▶ generators of degree 4:

$$H = \frac{1}{2}g^{\mu\nu}(x)p_\mu p_\nu + \frac{1}{2}\Gamma_{\mu\nu}^\beta(x)\theta^\mu\theta^\nu p_\beta + \frac{1}{16}R_{\alpha\beta\mu\nu}(x)\theta^\alpha\theta^\beta\theta^\mu\theta^\nu$$

$$\rightsquigarrow \text{SUSY algebra} \quad \frac{1}{4}\{\Theta, \Theta\} = H$$

# Graded spacetime mechanics

Graded Poisson algebra on  $T^*[2]M \oplus T[1]M$ :  $\{p_\mu, x^\nu\} = \delta_\mu^\nu$

$$\{\theta^\mu, \theta^\nu\} = 2g^{\mu\nu}(x) \quad \{p_\mu, \theta^\alpha\} = \Gamma_{\mu\beta}^\alpha \theta^\beta \quad \{p_\mu, p_\nu\} = \frac{1}{2}\theta^\beta \theta^\alpha R_{\beta\alpha\mu\nu}$$

Equations of motion with Hamiltonian (Dirac op.)  $\Theta = \theta^\mu p_\mu$

$$\frac{dA}{d\tau} = \frac{1}{2}\{\Theta, \{\Theta, A\}\} = \frac{1}{2}\{\{\Theta, \Theta\}, A\} - \frac{1}{2}\{\Theta, \{\Theta, A\}\} =: \{H, A\}$$

and derived Hamiltonian

$$H = \frac{1}{4}\{\Theta, \Theta\} = \frac{1}{2}g^{\mu\nu} p_\mu p_\nu + \frac{1}{2}\theta^\mu \theta^\nu \Gamma_{\mu\nu}^\beta p_\beta + \frac{1}{16}\theta^\alpha \theta^\beta \theta^\mu \theta^\nu R_{\alpha\beta\mu\nu}$$

For a torsion-less connection, only the first term is non-zero.

Derived anchor map applied to  $V = V_\alpha(x)\theta^\alpha$ :

$$h(V)f = \{\{V, \Theta\}, f\} = V_\alpha(x)g^{\alpha\beta}\partial_\beta f$$

# Graded spacetime mechanics

Equations of motion (cont'd)

$$\frac{dx^\mu}{d\tau} = \frac{1}{2}\{\Theta, \{\Theta, x^\mu\}\} = \{\frac{1}{2}g^{\alpha\beta}p_\alpha p_\beta, x^\mu\} = g^{\mu\nu}p_\nu$$

$$\frac{dp_\nu}{d\tau} = \{\frac{1}{2}g^{\alpha\beta}p_\alpha p_\beta, p_\nu\} = \frac{1}{2}(\partial_\mu g^{\alpha\beta})p_\alpha p_\beta = g\Gamma_\mu^{\alpha\beta}p_\alpha p_\beta$$

with *any* metric-compatible connection  $g\Gamma$ .

Geodesic equation:

$$\frac{d^2x^\mu}{d\tau^2} = \{\frac{1}{2}g^{\alpha\beta}p_\alpha p_\beta, g^{\mu\nu}p_\nu\} = -\frac{dx^\alpha}{d\tau} {}^{LC}\Gamma_{\alpha\beta}^\mu \frac{dx^\beta}{d\tau}$$

Nice warmup example and useful in its own right. For the grander scheme with  $B$ -field, dilaton, stringy symmetries, we need to double up ...

## Courant sigma model

standard Courant algebroid  $C = TM \oplus T^*M$

TFT with 3-dimensional membrane world volume  $\Sigma_3$

$$S_{\text{AKSZ}}^{(2)} = \int_{\Sigma_3} \left( \phi_i \wedge dX^i + \frac{1}{2} G_{IJ} \alpha^I \wedge d\alpha^J - h_I{}^i(X) \phi_i \wedge \alpha^I \right. \\ \left. + \frac{1}{6} C_{IJK}(X) \alpha^I \wedge \alpha^J \wedge \alpha^K \right)$$

embedding maps  $X : \Sigma_3 \rightarrow M$ , 1-form  $\alpha$ , aux. 2-form  $\phi$ , fiber metric  $G$ , anchor  $h$ , 3-form  $C$  (e.g.  $H$ -flux,  $f$ -flux,  $Q$ -flux,  $R$ -flux).

## Graded Poisson manifold $T^*[2]T[1]M$

- ▶ degree 0:  $x^i$  “coordinates”
- ▶ degree 1:  $\xi^\alpha = (\theta^i, \chi_i)$
- ▶ degree 2:  $p_i$  “momenta”

symplectic 2-form

$$\omega = dp_i \wedge dx^i + \frac{1}{2} G_{\alpha\beta} d\xi^\alpha \wedge d\xi^\beta = dp_i \wedge dx^i + d\chi_i \wedge d\theta^i$$

even (degree -2) Poisson bracket on functions  $f(x, \xi, p)$

$$\{x^i, x^j\} = 0, \quad \{p_i, x^j\} = \delta_i^j, \quad \{\xi^\alpha, \xi^\beta\} = G^{\alpha\beta}$$

metric  $G^{\alpha\beta}$ : natural pairing of  $TM$ ,  $T^*M$ :

$$\{\chi_i, \theta^j\} = \delta_i^j, \quad \{\chi_i, \chi_j\} = 0, \quad \{\theta^i, \theta^j\} = 0$$

## degree-preserving canonical transformations

- infinitesimal, generators of degree 2:

$$v^\alpha(x)p_\alpha + \frac{1}{2}M^{\alpha\beta}(x)\xi_\alpha\xi_\beta \rightsquigarrow \text{diffeos and } o(d, d)$$

- finite, idempotent (“coordinate flip”):  $(\tilde{\chi}, \tilde{\theta}) = \tau(\chi, \theta)$  with  $\tau^2 = \text{id}$   
 $\rightsquigarrow$  generating function  $F$  of type 1 with  $F(\theta, \tilde{\theta}) = -F(\tilde{\theta}, \theta)$ :

$$F = \theta \cdot g \cdot \tilde{\theta} - \frac{1}{2} \theta \cdot B \cdot \theta + \frac{1}{2} \tilde{\theta} \cdot B \cdot \tilde{\theta}$$

$$\chi = \frac{\partial F}{\partial \theta} = \tilde{\theta} \cdot g + \theta \cdot B, \quad \tilde{\chi} = -\frac{\partial F}{\partial \tilde{\theta}} = \theta \cdot g + \tilde{\theta} \cdot B$$

$$\Rightarrow \tau(\chi, \theta) = (\chi, \theta) \cdot \begin{pmatrix} g^{-1}B & g^{-1} \\ g - Bg^{-1}B & -Bg^{-1} \end{pmatrix}$$

$\rightsquigarrow$  generalized metric

## Generalized geometry as a derived structure

Cartan's magic identity:

$$\mathcal{L}_X = [i_X, d] \equiv i_X d + d i_X$$

Lie bracket  $[X, Y]_{\text{Lie}}$  of vector fields as a derived bracket:

$$[[i_X, d], i_Y] = [\mathcal{L}_X, i_Y] = i_{[X, Y]_{\text{Lie}}} \quad \text{with } [d, d] = d^2 = 0$$



## Generalized geometry as a derived structure

degree 3 “Hamiltonian”: Dirac operator

$$\Theta = \xi^\alpha h_\alpha^i(x) p_i + \underbrace{\frac{1}{6} C_{\alpha\beta\gamma} \xi^\alpha \xi^\beta \xi^\gamma}_{\text{twisting/flux terms}}$$

For  $e = e_\alpha(x) \xi^\alpha \in \Gamma(TM \oplus T^*M)$  (degree 1, odd):

- ▶ pairing:  $\langle e, e' \rangle = \{e, e'\}$
- ▶ anchor:  $h(e)f = \{\{e, \Theta\}, f\}$
- ▶ bracket:  $[e, e']_D = \{\{e, \Theta\}, e'\}$

## Generalized geometry as a derived structure

$$\begin{aligned}h(\xi_1) \langle \xi_2, \xi_2 \rangle &= \{ \{ \Theta, \xi_1 \}, \{ \xi_2, \xi_2 \} \} \\&= 2 \{ \{ \{ \Theta, \xi_1 \}, \xi_2 \}, \xi_2 \} = 2 \langle [\xi_1, \xi_2], \xi_2 \rangle \\&= 2 \{ \xi_1, \{ \{ \Theta, \xi_2 \}, \xi_2 \} \} = 2 \langle \xi_1, [\xi_2, \xi_2] \rangle\end{aligned}$$

$$\begin{aligned}[\xi_1, [\xi_2, \xi_3]] &= \{ \{ \Theta, \xi_1 \}, \{ \{ \Theta, \xi_2 \}, \xi_3 \} \} \\&= [[\xi_1, \xi_2], \xi_3] + [\xi_2, [\xi_1, \xi_3]] + \frac{1}{2} \{ \{ \{ \Theta, \Theta \}, \xi_1 \}, \xi_2 \}, \xi_3 \}.\end{aligned}$$

$$\{ \Theta, \Theta \} = 0 \quad \Leftrightarrow \quad \text{axioms of a Courant algebroid}$$

## Courant algebroid

vector bundle  $E \xrightarrow{\pi} M$ , anchor  $h : E \rightarrow TM$ ,  
bracket  $[-, -]$ , pairing  $\langle -, - \rangle$ , s.t. for  $e, e', e'' \in \Gamma E$ :

$$[e, [e', e'']] = [[e, e'], e''] + [e', [e, e'']] \quad (1)$$

$$2\langle [e, e'], e' \rangle \stackrel{(2a)}{=} h(e)\langle e', e' \rangle \stackrel{(2b)}{=} 2\langle [e', e'], e \rangle \quad (2)$$

Consequences:

$$[e, fe'] = h(e).f e' + f[e, e'] \quad (3)$$

$$h([e, e']) = [h(e), h(e')]_{\text{Lie}} \quad (4)$$

(2a+b) can be polarized, (1) and (3) define a Leibniz algebroid

## Standard Courant algebroid

Idea: Extension of the tangent bundle; unify symplectic, complex and Riemannian structures; string symmetries.

Treat vector fields and forms on equal footing:

$$E = TM \oplus T^*M \text{ "generalized tangent bundle"}$$

$$V = X + \xi = X^i(x)\partial_i + \xi_i(x)dx^i \in \Gamma E$$

With the Dorfman bracket

$$[X + \xi, Y + \eta]_D = [X, Y] + \mathcal{L}_X\eta - \iota_Y d\xi \quad (+\text{twisting/flux terms}),$$

the natural pairing  $\langle -, - \rangle$  of  $TM$  and  $T^*M$  and the projection  $h : E \rightarrow TM$  (anchor) we obtain a Courant algebroid.

Symmetries: diffeomorphisms,  $B$ -transform,  $\theta$ -transform

# Generalized Geometry and Gravity

## Generalized Metric

The pairing  $\langle -, - \rangle$  has signature  $(n, n)$ . An idempotent self-adjoint homomorphism  $\tau$  can turn it into a positive definite generalized metric

$$\mathbb{G}(V, W) := \langle \tau(V), W \rangle \quad (\mathbb{G}_{\alpha\beta}) = \begin{pmatrix} g - Bg^{-1}B & Bg^{-1} \\ -g^{-1}B & g^{-1} \end{pmatrix}$$

## Generalized Geometry and (super)gravity

established approach: choose Courant algebroid and follow the scheme

Generalized metric  $\rightarrow$  Bismut connection  $\rightarrow$  set torsion zero (add further conditions as needed)  $\rightarrow$  curvature  $\rightarrow$  equations of motion  $\leftrightarrow$  action

DFT approach: double spacetime  $\rightarrow$  universal action  $\rightarrow$  strong constraint

new alternative approach: graded geometry, deformation (this talk)

# Graded Geometry and Gravity

setup:  $T^*[2]T[1]M$  ("step 2") even bracket with odd variables  
deformation by a non-symmetric metric  $\mathcal{G} = j \circ (g + B) \circ h$

$$\{\chi_i, \chi_j\} = 0 \quad \rightarrow \quad \{\chi_i, \chi_j\}' = 2g_{ij}(x)$$

$\Rightarrow$  for  $X = X^i(x)\chi_i$  and  $v = v^i(x)p_i$ , the Poisson structure implies

$$\{v, X\}' = \nabla_v^{\mathcal{G}} X, \quad \{v, v'\}' = [v, v']_{\text{Lie}} + R(v, v')$$

$\{\Theta, \Theta\} = 0 \Leftrightarrow R(v, v') = 0$  (no curvature!) Weitzenböck connection

$$\nabla_i^{\mathcal{G}} \chi_j = -(\partial_i g_{jl}) \theta^l$$

the derived bracket involves the Levi-Civita connection  $\nabla^{\text{LC}}$  (no torsion!)

$$[X, Y]' = [X, Y]_D + 2g(\nabla^{\text{LC}} X, Y) + H(-, X, Y)$$

plus skew symmetric torsion  $H = dB$ .

# Graded Geometry and Gravity

generalized Koszul formula for nonsymmetric  $\mathcal{G} = g + B$

$$\begin{aligned}2g(\nabla_Z X, Y) &= \langle Z, [X, Y]' \rangle' \\&= X\mathcal{G}(Y, Z) - Y\mathcal{G}(X, Z) + Z\mathcal{G}(X, Y) \\&\quad - \mathcal{G}(Y, [X, Z]_{\text{Lie}}) - \mathcal{G}([X, Y]_{\text{Lie}}, Z) + \mathcal{G}(X, [Y, Z]_{\text{Lie}}) \\&= 2g(\nabla_X^{\text{LC}} Y, Z) + H(X, Y, Z)\end{aligned}$$

$\Rightarrow$  non-symmetric Ricci tensor

$$R_{jl} = R_{jl}^{\text{LC}} - \frac{1}{2} \nabla_i^{\text{LC}} H_{jl}^i - \frac{1}{4} H_{lm}^i H_{ij}^m \quad R = \mathcal{G}_{ij} g^{ik} g^{jl} R_{kl}$$

$\Rightarrow$  gravity action (closed string effective action) after partial integration:

$$S_{\mathcal{G}} = \frac{1}{16\pi G_N} \int d^d x \sqrt{-g} \left( R^{\text{LC}} - \frac{1}{12} H_{ijk} H^{ijk} \right)$$

# Graded Geometry and Gravity

This formulation consistently combines all approaches of Einstein: Non-symmetric metric, Weitzenböck and Levi-Civita connections, without any of the usual drawbacks.

The **dilaton**  $\phi(x)$  rescales the generalized tangent bundle. The deformation can be formulated in terms of vielbeins

$$E = e^{-\frac{\phi}{3}} \begin{pmatrix} 1 & 0 \\ g + B & 1 \end{pmatrix} \quad E^{-1} \partial_i E = \begin{pmatrix} -\frac{1}{3} \partial_i \phi & 0 \\ \partial_i (g + B) & -\frac{1}{3} \partial_i \phi \end{pmatrix}$$

Going through the same steps as before we find in  $d = 10$

$$S = \frac{1}{2\kappa} \int d^{10}x \, e^{-2\phi} \sqrt{-g} \left( R^{\text{LC}} - \frac{1}{12} H^2 + 4(\nabla\phi)^2 \right)$$



## Fully deformed Poisson structure on $T^*[2]T[1]M$

$$\begin{aligned}\{v, f\} &= v.f \\ \{V, W\} &= G(V, W) \equiv \langle V, W \rangle \\ \{v, V\} &= \nabla_v V \quad \leftarrow \text{connection metric wrt. } G \\ \{v, w\} &= [v, w]_{\text{Lie}} + R(v, w) \quad \leftarrow \text{curvature of } \nabla\end{aligned}$$

with

- ▶ degree 0:  $f(x)$
- ▶ degree 1:  $V = V^\alpha(x)\xi_\alpha$  “generalized vectors”  $\in \Gamma(TM \oplus T^*M)$
- ▶ degree 2:  $v = v^i(x)p_i$  “vector fields”  $\in \Gamma(TM)$

## general Hamiltonian

$$\Theta = \tilde{\xi}^\alpha h(\xi_\alpha) + \frac{1}{6} C_{\alpha\beta\gamma} \tilde{\xi}^\alpha \tilde{\xi}^\beta \tilde{\xi}^\gamma \quad \leftarrow \text{general flux (H,f,Q,R)}$$

# Graded Geometry and Gravity

## derived bracket

$$\{\{\{V, \Theta\}, W\}, X\} = \langle \nabla_V W, X \rangle - \langle \nabla_W V, X \rangle + \langle \nabla_X V, W \rangle + C(V, W, X)$$

$$\{\{\{\xi_\alpha, \Theta\}, \xi_\beta\}, \xi_\gamma\} = \underbrace{\Gamma_{\alpha\beta\gamma} - \Gamma_{\beta\alpha\gamma}}_{\text{torsion}} + \Gamma_{\gamma\alpha\beta} + C_{\alpha\beta\gamma} =: \Gamma_{\gamma\alpha\beta}^{\text{new}}$$

## “mother of all brackets”

$$\begin{aligned} [V, W] &= \nabla_V W - \nabla_W V + \langle \nabla V, W \rangle + C(V, W, -) \\ &= [V, W]_{\text{Lie}} + T(V, W) + \langle \nabla V, W \rangle + C(V, W, -) \end{aligned}$$

In order to obtain a regular Courant algebroid, impose

$$\{\Theta, \Theta\} = 0 \quad \Leftrightarrow \quad \nabla C + \frac{1}{2}\{C, C\} = 0, \quad G^{-1}|_h = 0, \dots$$

# Graded Geometry and Gravity

generalized connection (involves anchor  $h : E \rightarrow TM$ )

$$\nabla_V(fW) = (h(V)f)W + f\nabla_V W, \quad \nabla_{fV}W = f\nabla_V W$$

generalized Lie-bracket

$$[V, W]_{\text{Lie}} = h(V)W - h(W)V \equiv (V^i \partial_i W_\alpha(x) - W^i \partial_i V_\alpha(x)) \xi^\alpha$$

generalized torsion tensor

$$T(V, W) = \nabla_V W - \nabla_W V - [V, W]_{\text{Lie}}$$

generalized curvature tensor

$$R(V, W) = \nabla_V \nabla_W - \nabla_W \nabla_V - \nabla_{[V, W]_{\text{Lie}}}$$

## Summary + Discussion

- ▶ deformation: combines best aspects of Lagrange and Hamilton
- ▶ generalized geometry provides a perfect setting for the formulation of theories of gravity
- ▶ our approach is based on deformed graded geometry and is algebraic in nature: almost everything follows from associativity as unifying principle (which can be generalized)
- ▶ more traditional approaches are based on the generalized metric (with occasional covariance and uniqueness problems)
- ▶ string effective action without string theory; target space approach.

Thanks for listening!

